Dormand-Prince method

1. Summarize adaptive algorithms.

Answer:

- a. Using the current value of h, approximate the solution at $t_k + h$ using two different algorithms, one that is generally less accurate and another that is generally more accurate. Denote these approximations by y and z, respectively.
- b. Overestimate the error of the approximate *y* using 2|y z|.
- c. The error for a single step of the less accurate method will be of the form Ch^m for an appropriate power of *m*. Thus, we have that $Ch^m \approx 2|y-z|$, so $C \approx 2|y-z|/h^m$.
- d. Now, if we are willing to accept an error of ε_{abs} per unit time, then we are willing to accept $h\varepsilon_{abs}$ for that interval of width *h*.
- e. Now, if the error of y is greater than $h\varepsilon_{abs}$, the we should try again with a smaller value of h; however, if the error of y is less than $h\varepsilon_{abs}$, our step size is too small and we could have used a larger value of h. In the first case, we'll try again. In the second case, we'd like to use a larger value of h.
- f. What we really want is a scalar multiple of the interval width *ah* that gives the maximum acceptable error. Thus, we want to find an *a* so that $C(ah)^m = (ah)\varepsilon_{abs}$. We can substitute in the value of *C* above to get that $2|y z|/h^m \times (ah)^m = (ah)\varepsilon_{abs}$. We can solve this for *a* as follows:

$$a = m \sqrt[m-1]{\frac{h\varepsilon_{abs}}{2|y-z|}}.$$

- g. If $a \le 1$, we should try again with 0.9*ah*, but if a > 1, we will use *z* to approximate the solution at $t_k + h$ and with the next step we will use a step size of 0.9*ah*.
- 2. What algorithm does ode45 in Matlab use?

Answer: The Dormand-Prince method.

3. What are the errors of the two approximations of the Dormand-Prince method? What is m in the above calculation of a?

Answer: For a single step, the two approximations are $O(h^5)$ and $O(h^6)$, but such algorithms are always referred to their error after multiple steps. Thus, the value of *m* in this case is 5, so the calculation of *a* is the fourth root:

$$a = \sqrt[4]{\frac{h\varepsilon_{\rm abs}}{2|y-z|}}.$$

4. Would you ever expect to calculate even one step of the Dormand-Prince method in this course?

Answer: No. It is not unreasonable to ask for one step of the adaptive Euler-Heun method, but Dormand-Prince is an algorithm that should be implemented in a program.